

WHAT IS CLAIMED IS:

1. A distortion measurement method comprising:

a first formation step of repeating, $m \times n$ times,
shot exposure of arranging first marks on a

5 photosensitive substrate via a reticle and a projection
optical system in M rows and N columns at a
predetermined column interval and a predetermined row
interval, thereby forming first marks in $M \times m$ rows and
 $N \times n$ columns on the photosensitive substrate, M and m
10 being natural numbers which are relatively prime, N and
 n being natural numbers which are relatively prime, and
 $M > m$ and $N > n$;

a second formation step of repeating, $M \times N$
times, shot exposure of arranging second marks on the
15 photosensitive substrate via the reticle in m rows and
 n columns at the predetermined column interval and the
predetermined row interval, thereby forming second
marks in $M \times m$ rows and $N \times n$ columns on the
photosensitive substrate, the first and second marks
20 formed in the first and second formation steps forming
 $M \times m \times N \times n$ overlay marks;

a measurement step of measuring misalignment
amounts of the first and second marks for each of the M
 $\times m \times N \times n$ overlay marks; and

25 a calculation step of calculating a distortion
amount of the projection optical system on the basis of
the misalignment amounts measured in the measurement

step.

2. The method according to claim 1, wherein

letting p_x be the predetermined column interval
and p_y be the predetermined row interval,

5 in the first step, shot exposure is repeated at a
shot interval of $p_x \times N$ in a row direction and a shot
interval of $p_y \times M$ in a column direction, and

in the second step, shot exposure is repeated at
a shot interval of $p_x \times n$ in the row direction and a
10 shot interval of $p_y \times m$ in the column direction.

3. The method according to claim 1, wherein in the
calculation step, a distortion amount is calculated for
a ξ th overlay mark formed from an i th first mark of a
 k th shot in the first formation step and a j th second
15 mark of an l th shot in the second formation step by
solving $2 \times M \times m \times N \times n$ simultaneous equations
obtained by substituting misalignment amount
measurement values $\delta_x(\xi)$ and $\delta_y(\xi)$ in X and Y
directions that are measured in the measurement step
20 into

$$\delta_x(\xi) = dx_1(i) - dx_2(j) + ex_1(k) - ex_2(l) - \\ Y_1(i)\theta_1(k) + Y_2(j)\theta_2(l)$$

$$\delta_y(\xi) = dy_1(i) - dy_2(j) + ey_1(k) - ey_2(l) + \\ X_1(i)\theta_1(k) - X_2(j)\theta_2(l)$$

25 where

$dx_1(i)$, $dy_1(i)$: misalignment amounts of the i th first
mark

$dx_2(j)$, $dy_2(j)$: misalignment amounts of the j th second mark

$ex_1(k)$, $ey_1(k)$, $\theta_1(k)$: alignment errors of the k th shot in the first formation step

5 $ex_2(l)$, $ey_2(l)$, $\theta_2(l)$: alignment errors of the l th shot in the second formation step

$X_1(i)$, $Y_1(i)$: coordinates of the i th first mark within the shot

$X_2(j)$, $Y_2(j)$: coordinates of the j th second mark within
10 the shot.

4. The method according to claim 3, wherein when the simultaneous equations are solved in the calculation step, a respective sum of $dx_2(j)$, $dy_2(j)$, $ex_1(k)$, $ey_1(k)$, $\theta_1(k)$, $ex_2(l)$, $ey_2(l)$, and $\theta_2(l)$ is assumed to
15 be 0, and a respective sum of $X_2(l) \times ex_2(l)$, $Y_2(l) \times ey_2(l)$, $Y_2(l) \times ex_2(l)$, and $X_2(l) \times ey_2(l)$ is assumed to be 0, for all the overlay marks.

5. The method according to claim 1, wherein the misalignment amount includes a misalignment amount
20 between respective barycentric positions of the first and second marks which constitute the overlay mark.

6. A distortion measurement apparatus comprising:
control means for controlling an exposure
apparatus so as to form $M \times m \times N \times n$ overlay marks on
25 a photosensitive substrate by repeating, $m \times n$ times, shot exposure of arranging first marks on the photosensitive substrate via a reticle and a projection

optical system in M rows and N columns at a predetermined column interval and a predetermined row interval to form first marks in $M \times m$ rows and $N \times n$ columns on the photosensitive substrate, and by
5 repeating, $M \times N$ times, shot exposure of arranging second marks on the photosensitive substrate via the reticle in m rows and n columns at the predetermined column interval and the predetermined row interval to form second marks in $M \times m$ rows and $N \times n$ columns on
10 the photosensitive substrate, M and m being natural numbers which are relatively prime, N and n being natural numbers which are relatively prime, and $M > m$ and $N > n$;

measurement means for measuring misalignment
15 amounts of the first and second marks for each of the $M \times m \times N \times n$ overlay marks; and

calculation means for calculating a distortion amount of the projection optical system on the basis of the misalignment amounts of the first and second marks
20 which are measured for each of the $M \times m \times N \times n$ overlay marks.

7. The apparatus according to claim 6, wherein
letting p_x be the predetermined column interval and p_y be the predetermined row interval,
25 said control means repeats shot exposure at a shot interval of $p_x \times N$ in a row direction and a shot interval of $p_y \times M$ in a column direction to form the

first marks in the $M \times m$ rows and the $N \times n$ columns,
 and repeats shot exposure at a shot interval of $p_x \times n$
 in the row direction and a shot interval of $p_y \times m$ in
 the column direction to form the second marks in the M
 5 $\times m$ rows and the $N \times n$ columns.

8. The apparatus according to claim 6, wherein said
 calculation means calculates a distortion amount for a
 ξ th overlay mark formed from an i th first mark of a
 k th shot by said first formation means and a j th second
 10 mark of an l th shot by said second formation means by
 solving $2 \times M \times m \times N \times n$ simultaneous equations
 obtained by substituting misalignment amount
 measurement values $\delta_x(\xi)$ and $\delta_y(\xi)$ in X and Y
 directions that are measured by said measurement means
 15 into

$$\begin{aligned}\delta_x(\xi) &= dx_1(i) - dx_2(j) + ex_1(k) - ex_2(l) - \\ &\quad Y_1(i)\theta_1(k) + Y_2(j)\theta_2(l) \\ \delta_y(\xi) &= dy_1(i) - dy_2(j) + ey_1(k) - ey_2(l) + \\ &\quad X_1(i)\theta_1(k) - X_2(j)\theta_2(l)\end{aligned}$$

20 where

$dx_1(i), dy_1(i)$: misalignment amounts of the i th first
 mark

$dx_2(j), dy_2(j)$: misalignment amounts of the j th second
 mark

25 $ex_1(k), ey_1(k), \theta_1(k)$: alignment errors of the k th shot
 by said first formation means

$ex_2(l), ey_2(l), \theta_2(l)$: alignment errors of the l th shot

by said second formation means
 $X_1(i)$, $Y_1(i)$: coordinates of the i th first mark within
the shot
 $X_2(j)$, $Y_2(j)$: coordinates of the j th second mark within
the shot.

9. The apparatus according to claim 8, wherein when
said calculation means solves the simultaneous
equations, a respective sum of $dx_2(j)$, $dy_2(j)$, $ex_1(k)$,
 $ey_1(k)$, $\theta_1(k)$, $ex_2(l)$, $ey_2(l)$, and $\theta_2(l)$ is assumed to
be 0, and a respective sum of $X_2(l) \times ex_2(l)$, $Y_2(l) \times$
 $ey_2(l)$, $Y_2(l) \times ex_2(l)$, and $X_2(l) \times ey_2(l)$ is assumed to
be 0, for all the overlay marks.

10. The apparatus according to claim 6, wherein the
misalignment amount includes a misalignment amount
between respective barycentric positions of the first
and second marks which constitute the overlay mark.

11. An exposure apparatus comprising:

exposure means for transferring an image on a
reticle onto a wafer by exposure light; and

storage means for generating and storing a
correction value for exposure processing on the basis
of a distortion amount obtained by executing a
distortion measurement method defined in claim 1,

wherein the correction value is reflected in
exposure processing by said exposure means.

12. A device manufacturing method comprising steps
of:

installing manufacturing apparatuses for various processes including an exposure apparatus defined in claim 11 in a semiconductor manufacturing factory; and

manufacturing a semiconductor device by a plurality of processes using the manufacturing apparatuses.

13. A method comprising:

a first exposure step of exposing each of first shot regions on a substrate to a plurality of first marks aligned at a predetermined interval via a master and a projection optical system;

a second exposure step of exposing each of second shot regions on the substrate to a plurality of second marks aligned at the predetermined interval via the master and the projection optical system, the first and second shot regions being so arranged as to make positions of a plurality of transferred first and second marks on the substrate correspond to each other, the plurality of transferred first and second marks being formed due to said first and second exposure step respectively, and number of the transferred first marks in the first shot region being larger than number of the transferred second marks in the second shot region; and

a calculation step of calculating a distortion amount of the projection optical system based on a positional difference measured for the transferred

first and second marks which correspond to each other.

14. A storage medium storing a program which causes a computer to execute a method, the method comprising:

5 a first exposure step of exposing each of first shot regions on a substrate to a plurality of first marks aligned at a predetermined interval via a master and a projection optical system;

10 a second exposure step of exposing each of second shot regions on the substrate to a plurality of second marks aligned at the predetermined interval via the master and the projection optical system, the first and second shot regions being so arranged as to make positions of a plurality of transferred first and second marks on the substrate correspond to each other,

15 the plurality of transferred first and second marks being formed due to said first and second exposure step respectively, and number of the transferred first marks in the first shot region being larger than number of the transferred second marks in the second shot region;

20 and

a calculation step of calculating a distortion amount of the projection optical system based on a positional difference measured for the transferred first and second marks which correspond to each other.

25 15. An exposure apparatus comprising: an exposure unit which exposes a substrate to a master pattern via a projection optical system; and

a control unit which executes a method defined in claim 13 to obtain a distortion amount of the projection optical system, and controls an exposure process by said exposure unit based on the obtained
5 distortion amount.

16. A device manufacturing method comprising:

providing an exposure apparatus defined in claim 15; and

manufacturing a device using the exposure
10 apparatus.